TECHNICAL CONDITIONS FOR RADIO EQUIPMENT AT RADIONAVIGATION LAND STATIONS PROVIDING SATELLITE DETERMINATION ERROR CORRECTING INFORMATION

(Article 14 and Article 48.3 of the Ordinance Regulating Radio Equipment)

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The technical conditions for the radio equipment at radionavigation land stations that provide satellite determination error correcting information shall be stipulated pursuant to the provisions of Article 14 paragraph 3 and Article 48.3 item 3) of the Ordinance Regulating Radio Equipment (Radio Regulatory Commission Regulations No. 18 of 1950), as follows.

1 General conditions

- 1) The radio equipment shall be capable of transmitting the following information.
 - (1) The location of the position at which the determination error to be obtained by receiving emissions from the satellite of GPS (which refers to the overall global satellite positioning system; the same applies hereafter) is measured
 - (2) Information about the state of the satellite of GPS
 - (3) Null information of GPS (which refers to the state in which there is no information to be transmitted, or information to be transmitted when starting of information transmission is adjusted; the same applies hereafter)
 - (4) Almanac data of radionavigation land stations (which refers to the data concerning the position, frequency, and state of neighboring radionavigation land stations; the same applies hereafter)
 - (5) Information about the correction of the determination error to be obtained by receiving emissions from the satellite of GPS
 - (6) Special information
- 2) The category number of the satellite determination error correcting information shall be as indicated in the right-hand column in accordance with the category of the satellite determination error correcting information in the left-hand column.

Category	Category number
The location of the position at which the	3
determination error to be obtained by receiving	
emissions from the satellite of GPS is measured	
Information about the state of the satellite of	5
GPS	
Null information of GPS	6
Almanac data of radionavigation land stations	7
Information about the correction of the	9
determination error to be obtained by receiving	
emissions from the satellite of GPS	
Special information	16

3) The radio equipment shall be capable of transmitting the information for testing or adjusting it.

2 Electric Conditions

- 1) The composition of the transmitting signal shall be as shown in Fig. 1 to Fig. 6.
- 2) The upper limit of the permissible values for the antenna power shall be 10%, and the lower limit shall be 20%.

Fig. 1 Composition of the signal of the location at the position at which the determination error to be obtained by receiving emissions from the satellite of GPS is measured (the signal shall consist of a first signal and a second signal)

The first signal;

		MSB	LSB	MSB LSB	
The first word	Pre-code	Category	of	Identification number of reference	Error
	01100110	satellite-deter	rmination	equipment (which refers to the	detecting
		error	correcting	receiving equipment that measures	code
		information	(Note 1)	a determination error; the same	
				applies hereafter) (Note 2)	
	$\leftarrow 1 \text{ to } 8 \rightarrow $	\leftarrow 9 to	14 →	$\leftarrow \qquad 15 \text{ to } 24 \qquad \rightarrow \qquad$	$\leftarrow 25 \text{ to } 30 \rightarrow$
Bit number					

	MSB LS	3	MSB LSB		
The second word	Modified Z	Serial number	Number of	State of	Error detecting
	count (Note 3)	(Note 4)	words that are	reference	code
			expected to be	equipment (Note	
			transmitted	6)	
			(Note 5)		
Bit number	$\leftarrow 1 \text{ to } 13 \rightarrow$	$\leftarrow 14 \text{ to } 16 \rightarrow$	$\leftarrow 17 \text{ to } 21 \rightarrow$	$\leftarrow 22 \text{ to } 24 \rightarrow$	$\leftarrow 25 \text{ to } 30 \rightarrow$

- "MSB": Most significant bit
- "LSB": Least significant bit
- Note 1 The category of satellite determination error correcting information shall be as shown in the table below.

Category number	Category	Bit indication
3	The location of the position at which the determination error to be	000011
	obtained by receiving emissions from the satellite of GPS is measured	
5	Information about the state of the satellite of GPS	000101
6	Null information of GPS	000110
7	Almanac data of radionavigation land stations	000111
9	Information about the correction of the determination error to be	001001
	obtained by receiving emissions from the satellite of GPS	
16	Special information	010000

- Note 2 Identification numbers that are assigned by the International Association of Marine Aids to Navigation and Lighthouse Authorities (IALA) shall be used.
- Note 3 The modified Z count shall indicate the reference time of satellite error correcting information. The modified Z count shall begin with 0 at the start of each GPS time calculation, the maximum value shall be 3,599.4 seconds, and the resolution shall be 0.6 second. The modified Z count shall be used to calculate the GPS time at a user's receiving equipment as in any other time calculation.
- Note 4 The serial number shall increase by 1 each time satellite-determination error correcting information is transmitted, and shall be used for synchronization.
- Note 5 The number of the words that are expected to be transmitted shall indicate that "N" words are transmitted in succession to the second word.
- Note 6 "111" shall indicate that the reference equipment does not operate properly, and "110" shall indicate that the transmission of radionavigation land stations is not monitored.

The second signal;

	MSB					
The third word	ECEF (Not	e) X- coordinates		Error c	detecting co	de
Bit number	←	1 to 24	\rightarrow	~	25 to 30	\rightarrow

LSB MSB							
The fourth word	ECEF	Х-	ECEF	Y-	Error detecting code		
	coordinates		coordinates				
	(continued)						
Bit number	\leftarrow 1 to 8	\rightarrow	$\leftarrow 9 \text{ to } 24$	\rightarrow	$\leftarrow 25 \text{ to } 30 \rightarrow $		

LSB MSB						
The fifth word	ECEF	Y-	ECEF	Z-	Error detecting code	
	coordinates		coordinates			
	(continued)					
Bit number	\leftarrow 1 to 16	\rightarrow	$\leftarrow 17 \text{ to } 24$	\rightarrow	$\leftarrow 25 \text{ to } 30 \rightarrow $	

The sixth word	ECEF Z- coordinates (continued)			Error	Error detecting code		
Bit number	←	1 to 24	\rightarrow	←	25 to 30 \rightarrow		

Note: "ECEF" shall indicate the earth center/earth fixed orthogonal axial system in the WGS-84 coordinate system.

Fig. 2 Composition of the signal of the information about the state of the satellite of GPS (the signal shall consist of a first signal and a second signal)

The first signal;

The first signal shall be the same as the first signal shown in Fig. 1.

The second signal;

The second signal shall consist of one word for each satellite, as follows (the conditions for each signal shall be as shown in the Table below).

(Note)	Preliminary	Satellite		State	C/N ₀		Acquisition of	X	Time to an	Pending	Error
The		identification		data			new navigation		abnormal		detecting
N ₁ th+		number					data		state		code
two											
words											
Bit	1	2 to 6	7	8 to	11 to	16	17	18	19 to 22	23 and	25 to 30
number				10	15					24	

Data issue number linked Compulsorily handled as a normal satellite Warning of a predicted abnormal state

Note: N_1 shall indicate the number of satellites.

Table Conditions for each signal

Signal	Bit number	Condition
Preliminary	1	The preliminary signal shall be used when the number of
		satellites exceeds 32 in the future.
Satellite	2 to 6	The satellite identification number shall indicate 1 to 32 (32
identification		shall be "0" for all the bits) in the standard form.
number		
Data issue number	7	When the bit indication is "0," the data issue number linked
linked		signal shall indicate that the navigation data in the issue
		number of the ephemeris data (which refers to the data of
		orbit information, etc. of each satellite; the same applies
		hereafter) of the signal shown in Fig. 5 must be referred to.
State data	8 to 10	The state data shall indicate the state of the navigation data
		of satellites. When the bit indication is "000," the state data
		shall indicate that all the data are normal, and that when any
		of the bit indications is "1," all or part of the state of the
		navigation data of satellites is abnormal.
C/N ₀	11 to 15	C/N ₀ shall be the signal to noise ratio of a satellite signal
		measured with the reference equipment. The unit shall be 1
		[dB - Hz], and shall indicate the range of 25 to 55 $[dB - Hz]$.
		The bit indication "00000" shall indicate that a satellite
		signal has not been captured, "00001" shall indicate the
		lowest value of 25 [dB – Hz], and "11111" shall indicate the
		highest value of $55 [dB - Hz]$.

Compulsorily	16	The signal compulsorily handled as a normal satellite
handled as a normal		shall indicate that even if the navigation data of a
satellite		satellite indicates an abnormal value when the bit
		indication is "1," the equipment that uses DGPS
		neglects the abnormal navigation data and considers
		it to be normal.
Acquisition of new	17	The acquisition of new navigation data shall indicate that
navigation data		when the bit indication is "1," the reference equipment
		acquires new navigation data of a satellite and is in the
		process of producing a dummy distance correcting value. It
		shall indicate that the serial number of the signal shown in
		Fig. 5 is expected to be updated.
Warning of a	18	The warning of a predicted abnormal state shall indicate that
predicted		when the bit indication is "1," the state of the navigation data
abnormal state		of a satellite is expected to become abnormal. The outline of
		the time during which the state of the navigation data is
		normal shall be indicated in 4 bits from the next digit.
Time to an	19 to 22	Refer to bit number 18. The time to an abnormal state shall
abnormal state		indicate the time range from 0 to 75 minutes (the unit is in
		five minutes). "0000" shall indicate that the state of the
		navigation data of a satellite becomes abnormal immediately,
		and "1111" shall indicate that it will become abnormal 75
		minutes later.

Fig. 3 Composition of the signal of the null information of GPS (the signal shall consist of a first signal and a second signal)

The first signal;

The first signal shall be the same as the first signal shown in Fig. 1.

The second signal;

This signal shall not include any parameter, shall continue transmission whenever necessary, and shall be used for the maintenance of the circuit. The purpose of transmitting this signal is to use it when the information that a radionavigation land station transmits has not been prepared yet, or when the time for starting the transmission of information should be adjusted.

This signal shall include first two words with N = "0" or N = "1" as the number of words that are expected to be transmitted by making the number of words to be transmitted either odd-numbered or

even-numbered, as in the composition of other transmission signals. When N = "1," the 24-digit data bit in the word following the first two words shall be data with "1" and "0" one after the other. The error detecting signal shall properly operate as in the composition of other transmission signals.

Fig. 4 Composition of the signal of almanac data of radionavigation land stations (the signal shall consist of a first signal and a second signal)

The first signal;

The first signal shall be the same as the first signal shown in Fig. 1. The second signal;

(Note 5)	Latitude (Note 1)	Longitude (higher-rank	Error detecting code
$3rd N_b word$		byte) (Note 1)	
Bit number	1 to 16	17 to 24	25 to 30

$3rd N_b + one$	Longitude	Usage range of a	Frequency	Error detecting
word	(lower-rank byte)	radionavigation	(higher-rank 6	code
	(Note 1)	land station	bits) (Note 2)	
Bit number	1 to 8	9 to 18	19 to 24	25 to 30

Transmission coding (the data bit shall be "0")									
	Synchronization identification (the data bit shall be "1")								
State of a radi	onavigation land sta	tion	Modulation method (th	ne data bit shall be "0")	\	$\langle \rangle$	\backslash		
3rd N _b +	Frequency	♦	Identification	Transmission rate			\mathbf{A}	Error	
two words	(lower-rank 6		number of a	(Note 5)				detecting	
	bits) (Note 2)		radionavigation land					code	
			station that transmits						
			information (Note 4)						
Bit	1 to 6	7	9 to 18	19 to 21	22	23	24	25 to 30	
number		and							
		8							

- Note 1 The "+" value shall indicate the north latitude in the case of latitude, and the east longitude in the case of longitude.
- Note 2 The unit shall be 100 Hz.
- Note 3 The state of a radionavigation land station shall be as follows.

Bit indication	Number	State
"00"	(0)	It is in normal operation.
"01"	(1)	It is operated under non-perfect surveillance.
"10"	(2)	There is no information provided about it.
"11"	(3)	It cannot be used.

Note 4 The identification numbers that are assigned by the International Association of Marine Aids to Navigation and Lighthouse Authorities (IALA) shall be used.

Note 5 The transmission rate shall be as shown in the table below.

Bit indication	Number	Transmission rate
"001"	(1)	50 bits/s
"010"	(2)	100 bits/s
"101"	(5)	200 bits/s

Note 6 N_b shall indicate the number of radionavigation land stations that are included in almanac data.

Fig. 5 Composition of the signal of the information about the correction of the determination error obtained by receiving emissions from the satellite of GPS (the signal shall consist of a first signal through a third signal);

The first signal

The first signal shall be the same as the first signal shown in Fig. 1. The second signal;

3rd, 8th, 13th,	Designation of	User	Satellite	Dummy	Error
or 18th word	unit	distance	identification	distance	detecting code
		error	number	correcting	
				value (Note 1)	
Bit number	1	2 and 3	4 to 8	9 to 24	25 to 30

4th, 9th,	Dummy	Issue	Designation	User	Satellite	Error
14th, or	distance	number of	of unit	distance	identification	detecting
19th word	variation	ephemeris		error	number	code
	ratio	data				
Bit number	(Note 2)					
	1 to 8	9 to 10	17	18 and 19	20 to 24	25 to 30

5th, 10th, 15th, or 20th	Dummy dista	ince	Dummy	distance	Error detecting code
word	correcting value		variation ratio		
Bit number	1 to 16		17 to 24		25 to 30

6th, 11th,	Issue	Designation	User	Satellite	Dummy	Error
16th, or	number of	of unit	distance	identification	distance	detecting
21st word	ephemeris		error	number	correcting	code
	data				value	
					(higher-rank	
					bits)	
Bit number	1 to 8	9	10 and	12 to 16	17 to 24	25 to 30
			11			

7th,	12th,	Dummy	distance	Dummy	distance	Issue	number	of	Error
17th, or	22nd	correcting	value	variation ra	atio	ephem	eris data		detecting
word		(lower-rank b	bits)						code
Bit numb	er	1 to 8		9 to	16	17	to 24		25 to 30

Note 1 The bit indication of "100000000000000" shall indicate that a problem is occurring.

Note 2 The bit indication of "10000000" shall indicate that a problem is occurring.

The third signal;

When the number of satellites, N_1 , cannot be divided by 3, it shall be compensated for by either word out of the following two words in order to complete the information about the correction of a satellite error.

Nth + two words	Dummy distance	Issue number of	Dummy bits	Error detecting
When $N_1 = 1, 4$,	variation ratio	ephemeris data		code
7, or 10				
Bit number	1 to 8	9 to 16	17 to 24	25 to 30

Nth + two words	Issue number of	Dummy bits	Dummy bits	Error detecting
When $N_1 = 2, 5,$	ephemeris data			code
8, or 11				
Bit number	1 to 8	9 to 16	17 to 24	25 to 30

Fig. 6 Composition of special information of GPS (the information shall consist of a first signal and a second signal)

The first signal;

The first signal shall be the same as the first signal shown in Fig. 1. The second signal;

I	MSB LSB	MSB LSB	MSB LSB	
(Note 1)	Alphanumeric	Alphanumeric	Alphanumeric	Error detecting
N + two words	(Note 2)			code
Bit number	1 to 8	9 to 16	17 to 24	25 to 30

Note 1 N shall be a bit number from 1 to 28.

Note 2 The alphanumeric shall be based on the ASCII code.

Reference: Article 48.3 of the Ordinance Regulating Radio Equipment shall be brought down to Article 49 pursuant to the MPHPT Ordinance of 2001.